

N F P A

Fluid Power

VEHICLE

Challenge



NFPA
Education and
Technology
Foundation

FINAL PRESENTATION &
DESIGN REVIEW
THE FLUID MECHANICS
TEXAS A&M UNIVERSITY
APRIL 24th, 2026



MEET THE TEAM



Jackson Perniciaro
Project Manager



Omar Khalil
Manufacturing Lead



Wesley George
Testing Lead



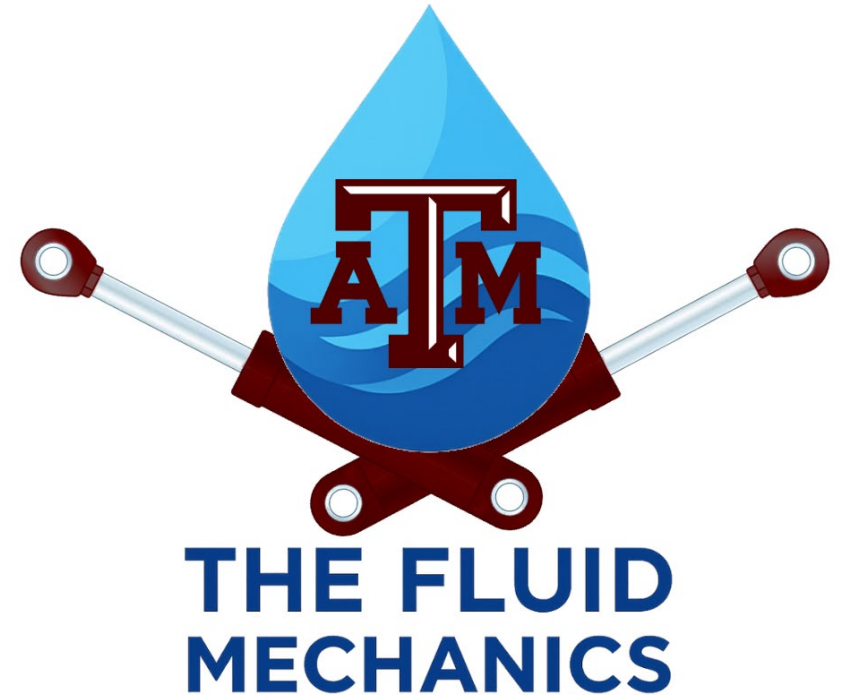
Mathew Manginelli
Engineering Lead



Ulises Arreola
System Integration Lead



Sri Kotaru
Safety Lead



ADVISORS & MENTORS



Mr. Eric Jensen
Industry Mentor



Gary D. Bradley
Faculty Advisor

Mr. Tony Henum
Industry Mentor

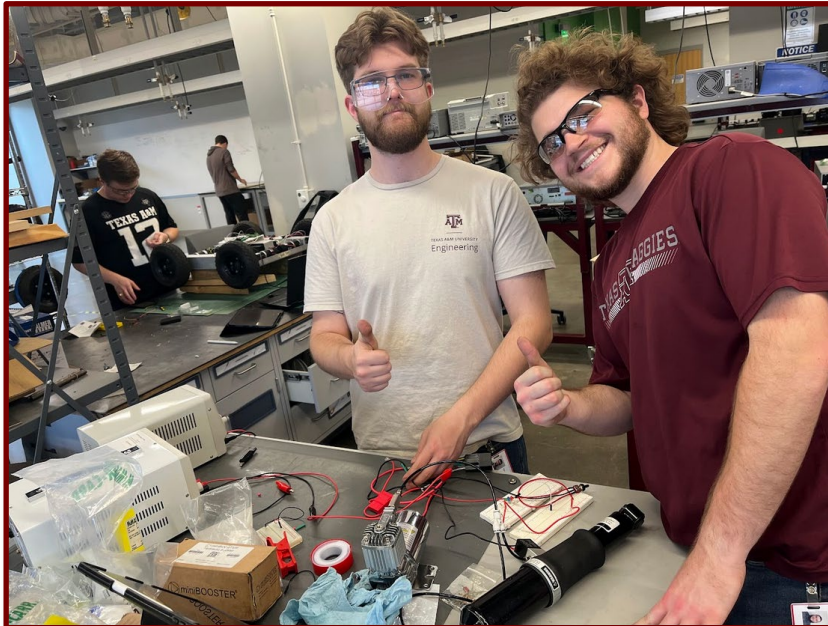
VEHICLE CONSTRUCTION

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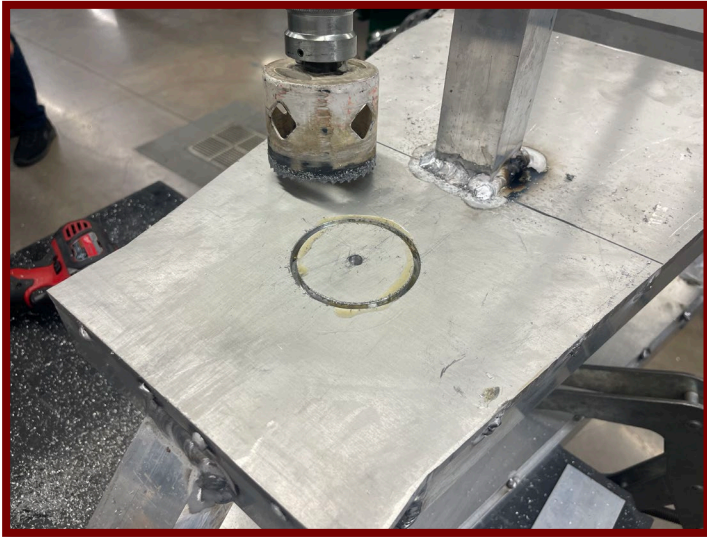


VEHICLE CONSTRUCTION

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VEHICLE CONSTRUCTION



Cutout for Accumulator and Reservoir ports



Accumulator mount on Chassis shelf



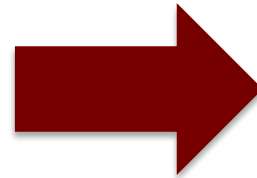
-06 JIC Bulkhead Manifold/Regen



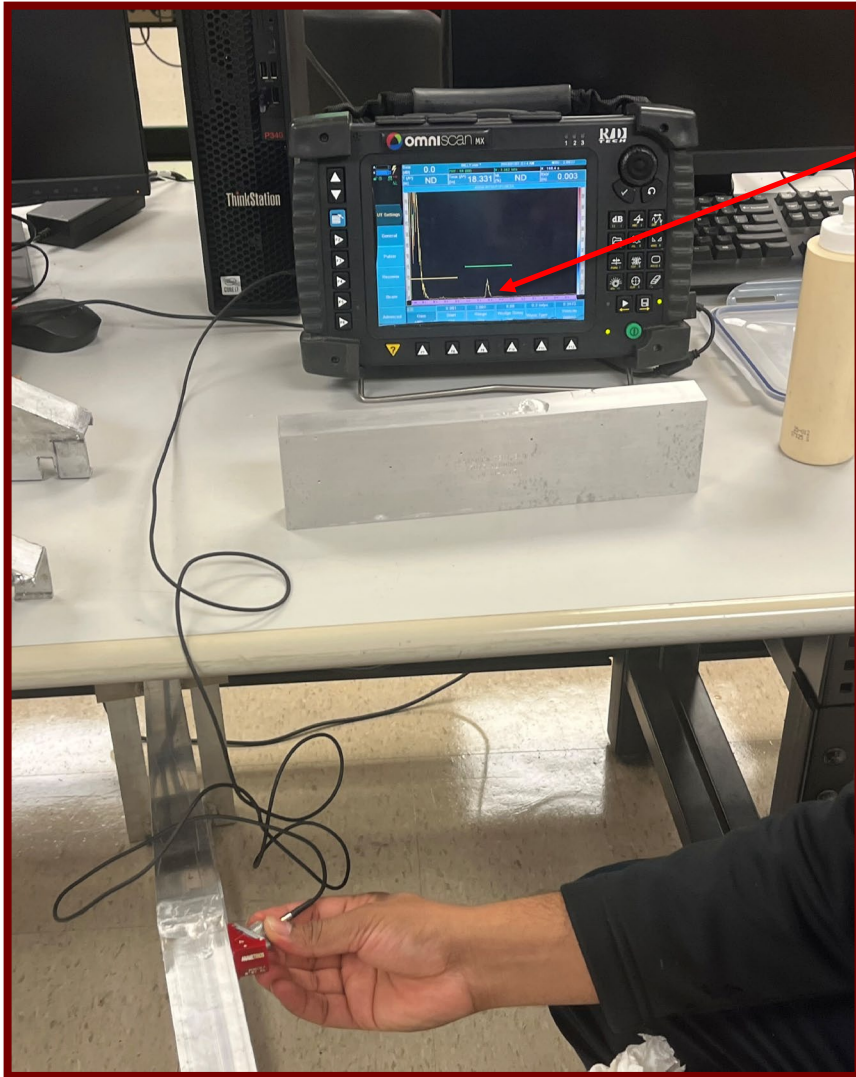
-10 JIC Bulkhead Pump Inlet

Completed PVC Reservoir and mounting position

VEHICLE CONSTRUCTION



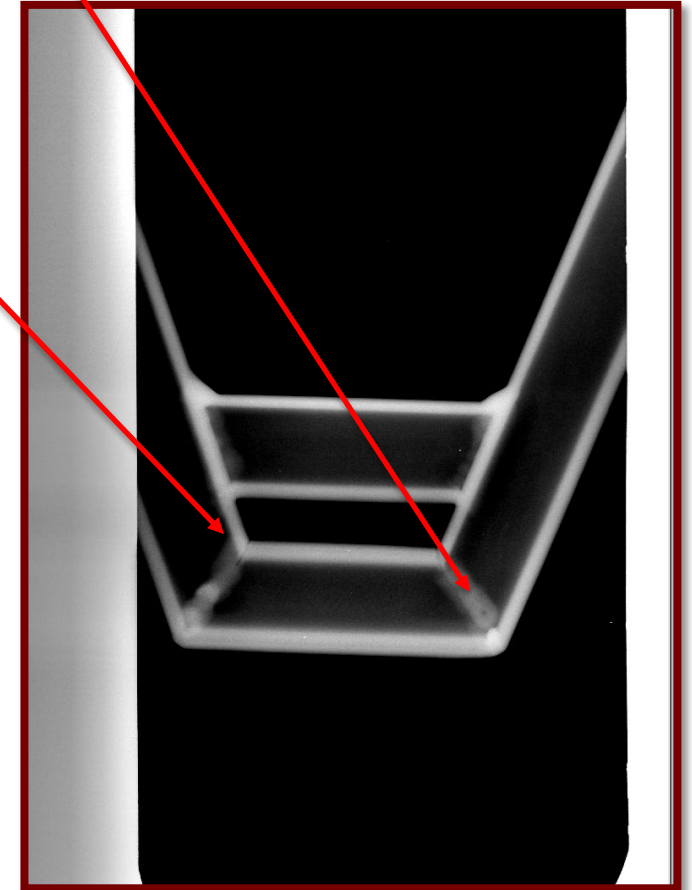
VEHICLE TESTING - WELDING



Backwall Echo

Discontinuity 1

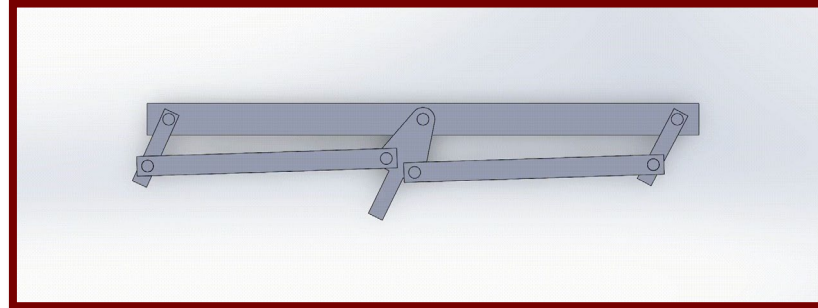
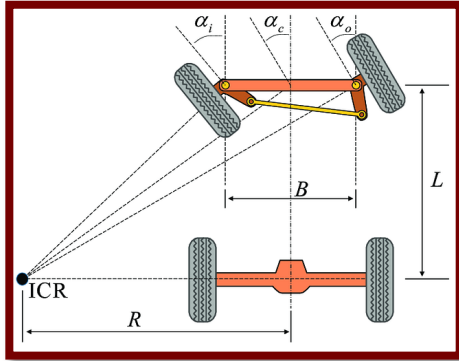
Discontinuity 2



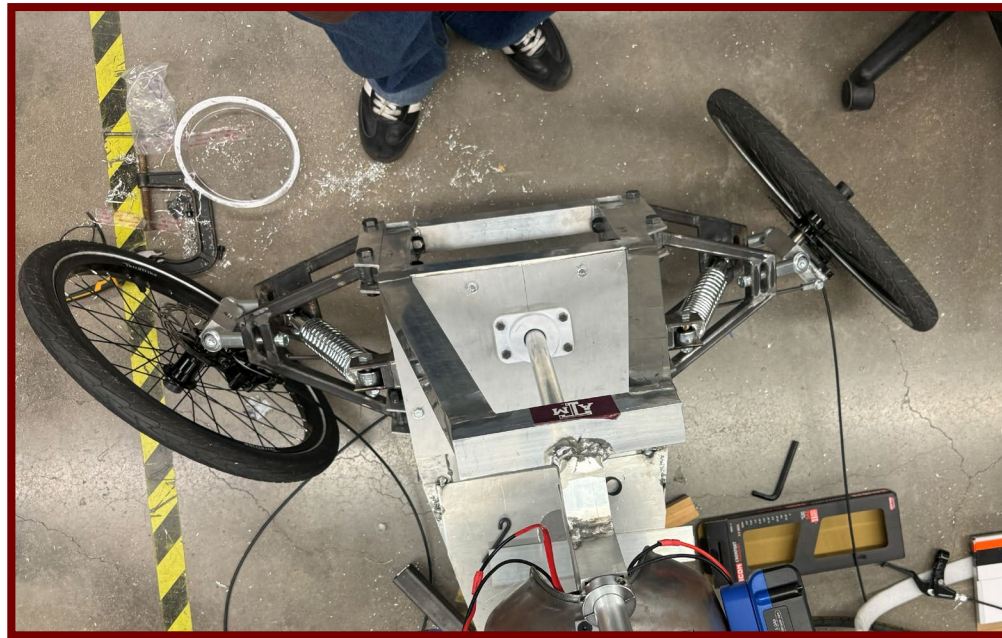
VEHICLE TESTING - MANUEVERABILITY



Ackermann Steering



Given			
Max Wheel Angle	58	degrees	
Wheelbase	7	ft	
Front Track Width	30	inches	
Turning Radius	5.624	ft	
Outside Wheel Angle	0.794	45.520	degrees
Inside Wheel Angle	1.012	58	degrees
Lever Arms			
Tie Rod Lever	3.250	inches	
Outside Articulation	2.319	inches	
Inside Articulation	2.756	inches	
Difference	0.437	inches	



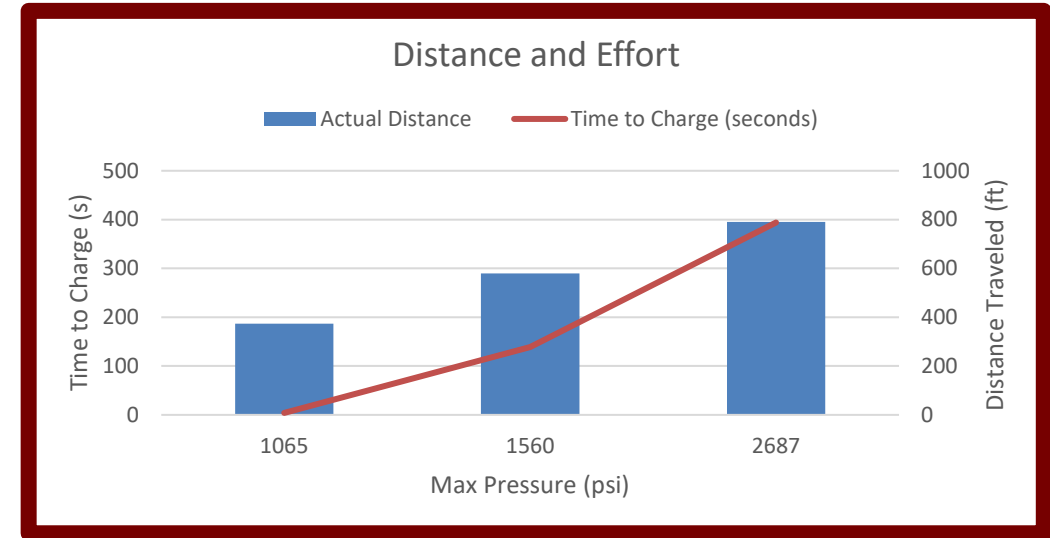
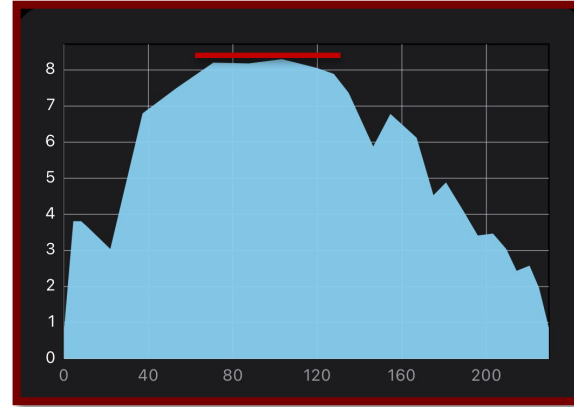
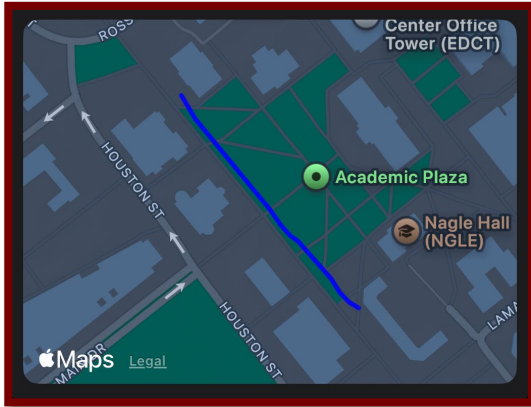
VEHICLE TESTING

EFFICIENCY/SPEED



791 [ft] | 0.15 [mi]

8.4 [m/s] | 18.79 [mph]



Gearbox	Ratio	Train Value High	CVT High rpm	High Torque	CVT High Speed (mph)
1st	1.82	1.7937	44.6015	645.7177	3.4499
2nd	1.47	1.4487	55.2209	521.5412	4.2713
3rd	1.19	1.1728	68.2141	422.2001	5.2763
4th	0.95	0.9363	85.4471	337.0505	6.6093
5th	0.76	0.7490	106.8089	269.6404	8.2617
6th	0.62	0.6110	130.9271	219.9698	10.1272
7th	0.49	0.4829	165.6628	173.8471	12.8140
8th	0.4	0.3942	202.9370	141.9160	15.6971
9th	0.32	0.3154	253.6712	113.5328	19.6214

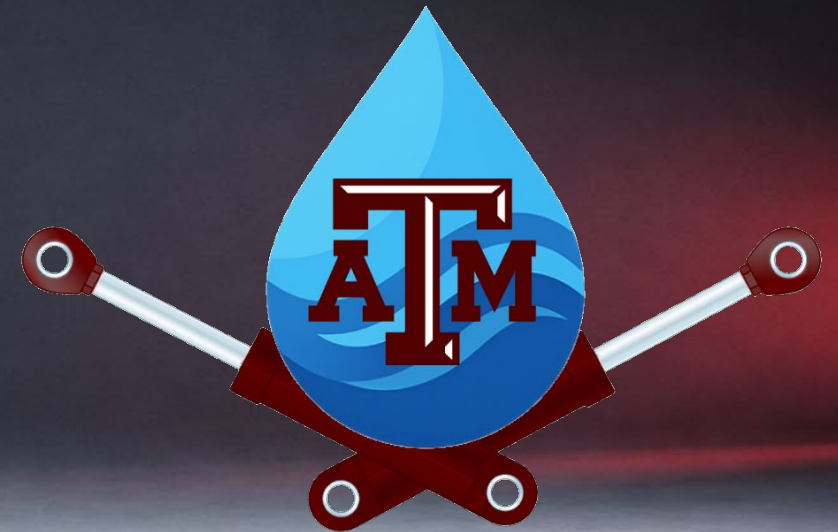
Motor: 12 Teeth
Wheel: 45 Teeth

Gearbox	Ratio	Train Value High	CVT High rpm	High Torque	CVT High Speed (mph)
1st	1.82	1.1958	66.9023	430.4785	5.1749
2nd	1.47	0.9658	82.8314	347.6942	6.4070
3rd	1.19	0.7819	102.3212	281.4667	7.9145
4th	0.95	0.6242	128.1707	224.7003	9.9140
5th	0.76	0.4993	160.2134	179.7602	12.3925
6th	0.62	0.4074	196.3906	146.6465	15.1908
7th	0.49	0.3219	248.4943	115.8981	19.2210
8th	0.4	0.2628	304.4055	94.6107	23.5457
9th	0.32	0.2102	380.5068	75.6885	29.4321

Motor: 12 Teeth
Wheel: 30 Teeth

VEHICLE DESIGN REVIEW

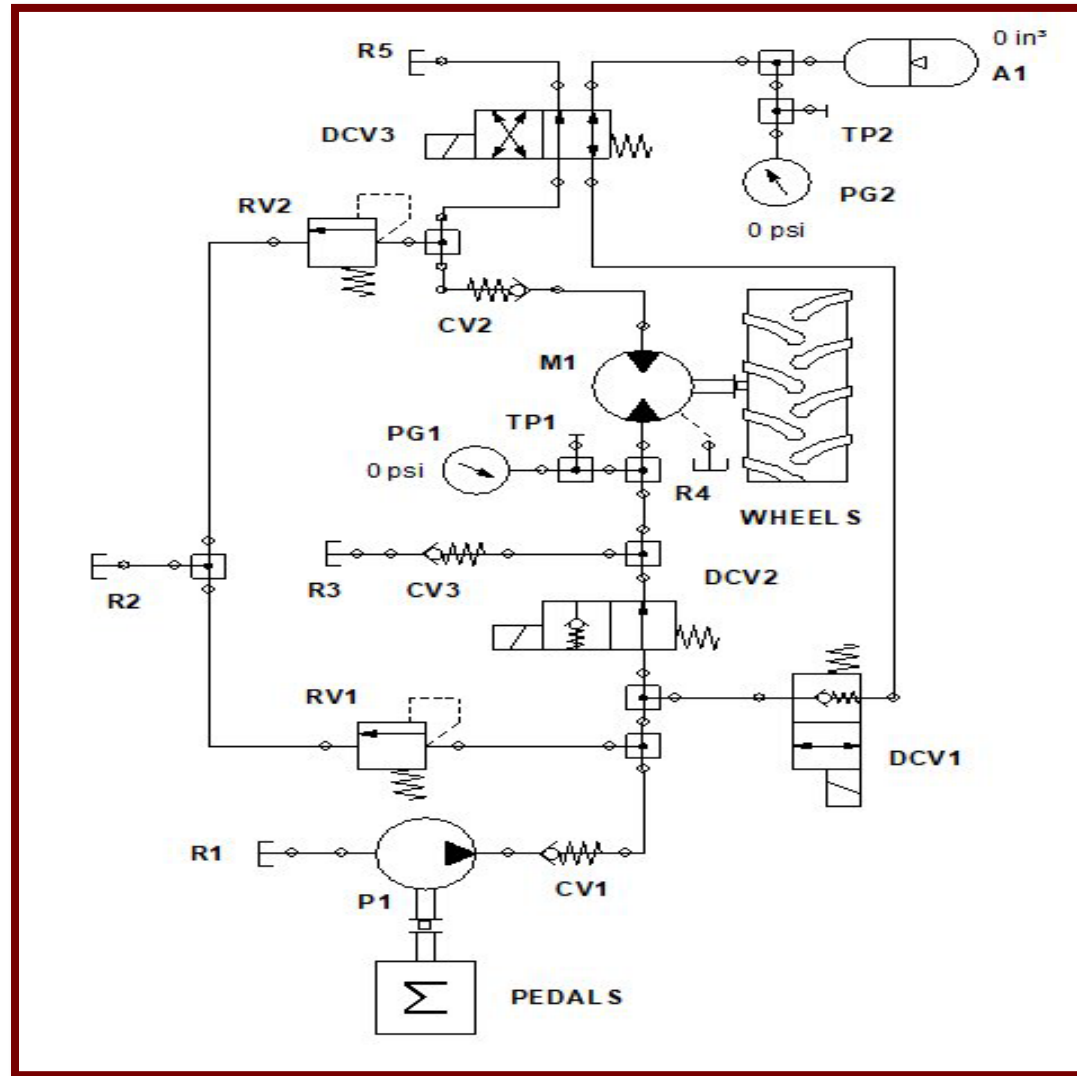
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**THE FLUID
MECHANICS**

TEAM GATR 2024-2025

HYDRAULICS DESIGN



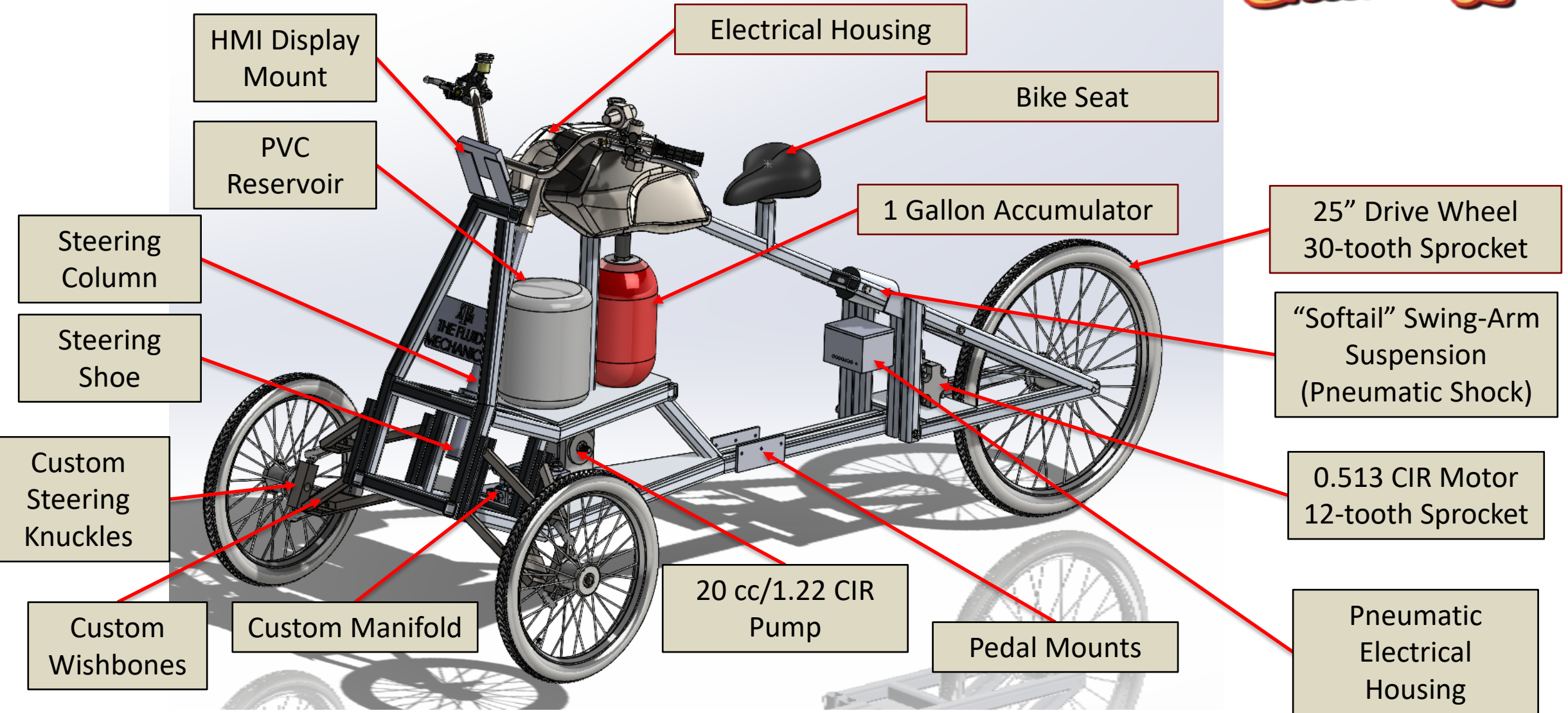
TEAM GATR 2024-2025

ADVANTAGES & DISADVANTAGES

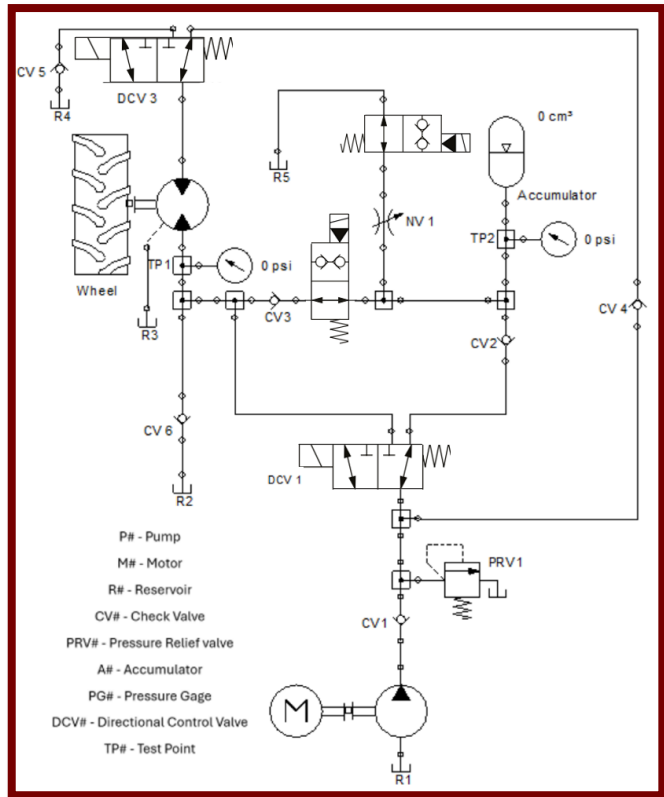


Advantages	Disadvantages
Implemented gearbox	Not all gearbox ratios could be used
Convenient electronic placement	No implementation of CVT
Lightweight	No implementation of Manifold
Fairly Efficient hydraulic circuit	Multiple components attached with little foresight
Compact Implementation	No use of Pneumatics

MECHANICAL DESIGN

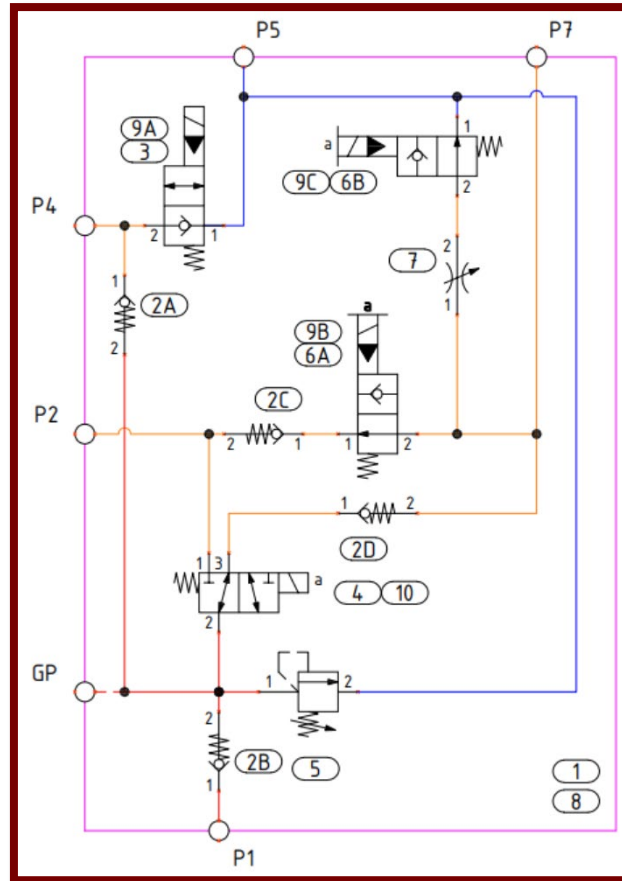


HYDRAULIC DESIGN



8th Iteration Schematic

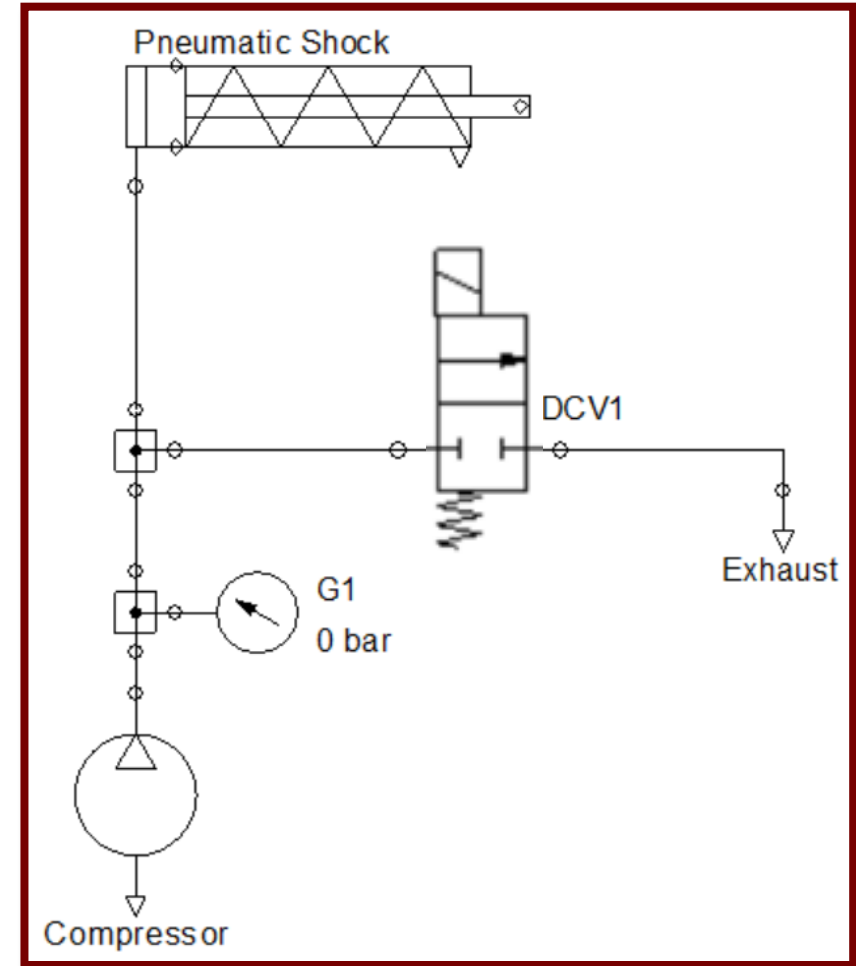
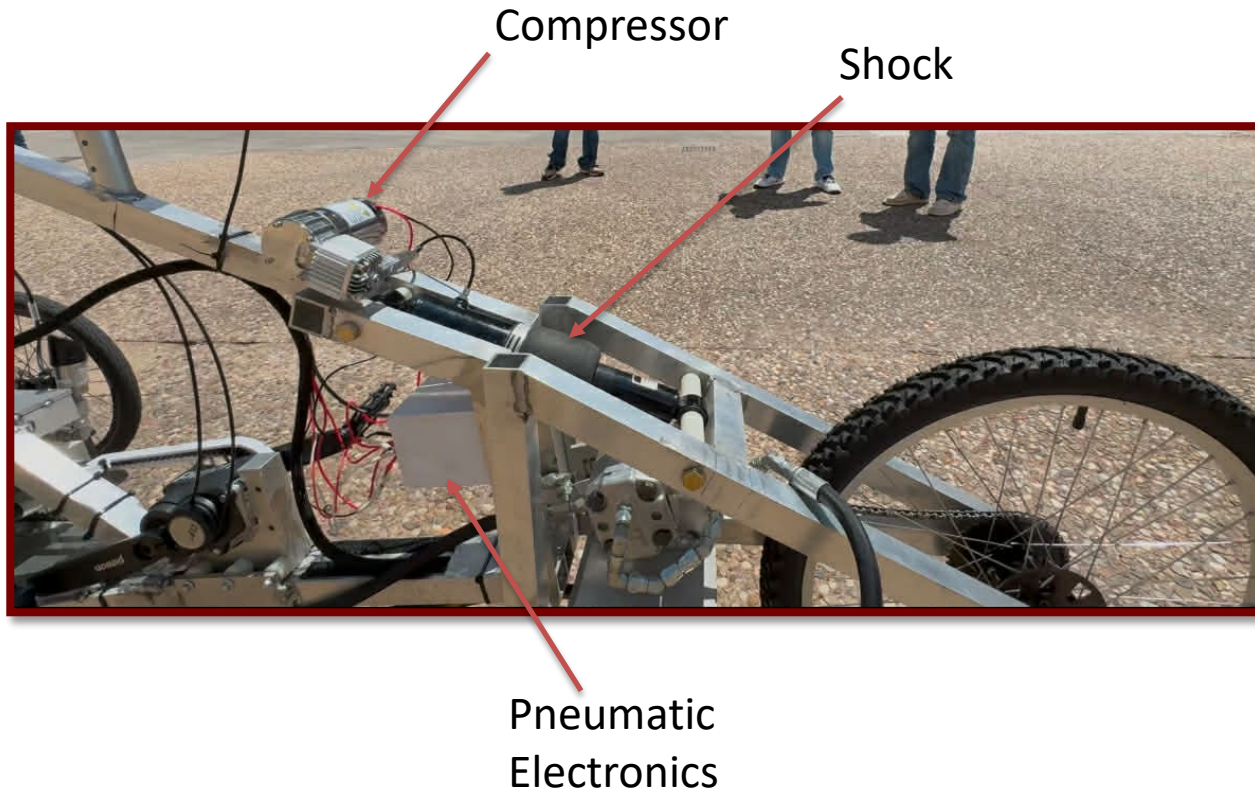
- Added Needle Valve to bleed Accumulator
- Default “Kill Switch” – Failsafe
- Design Approved by Team’s Industry Mentor Tony Hennum and Technical Liaison Ernie Parker



Updated Schematic w/Manifold

- Replaced SBV11 with SVP08
- Removed CV5
- DCV3 replaced with 2-way poppet valve
- P5 acts as common reservoir return

PNEUMATIC DESIGN

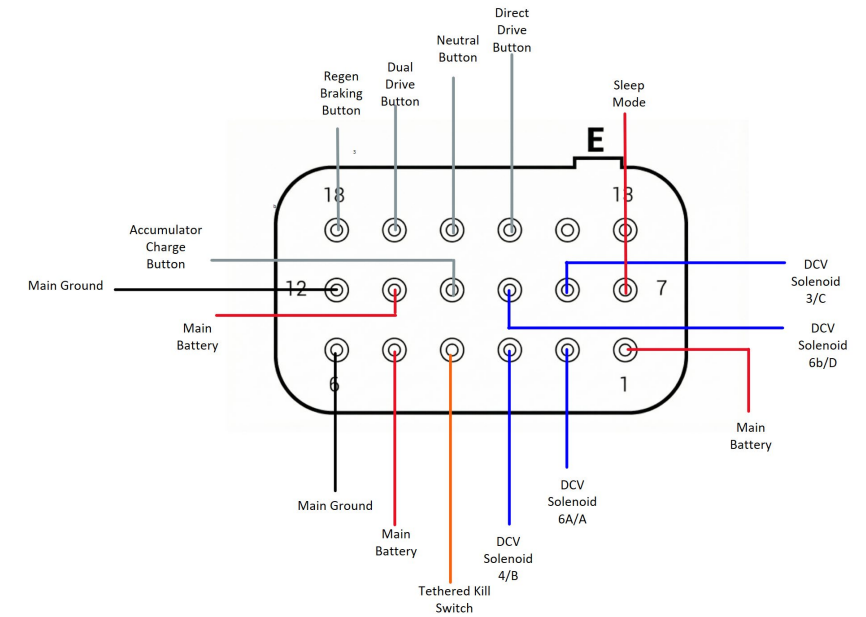
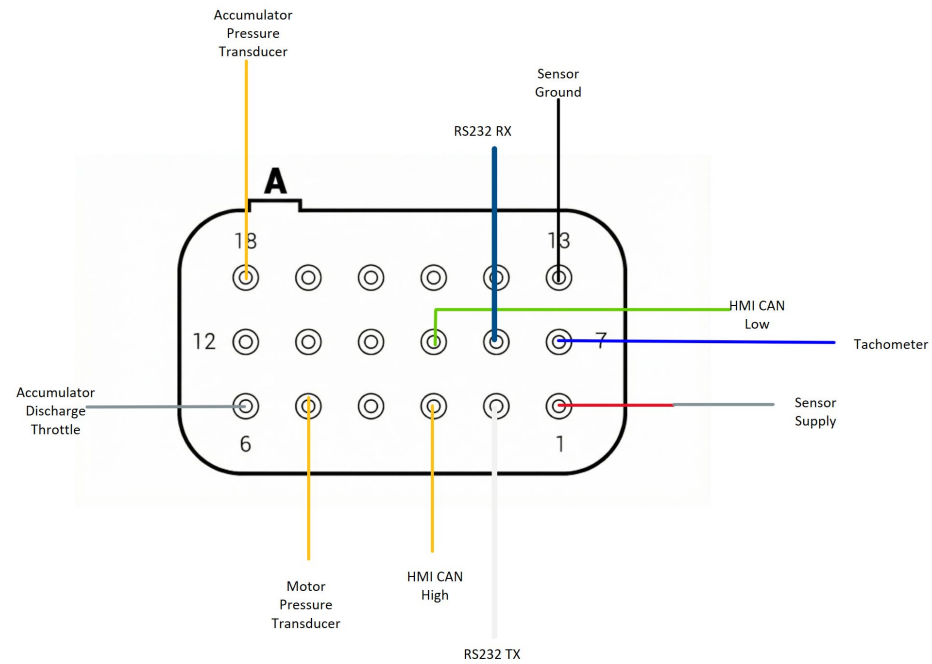
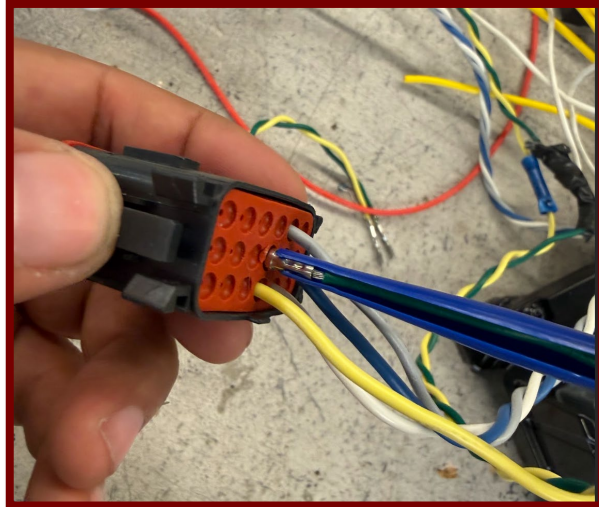


ELECTRICAL

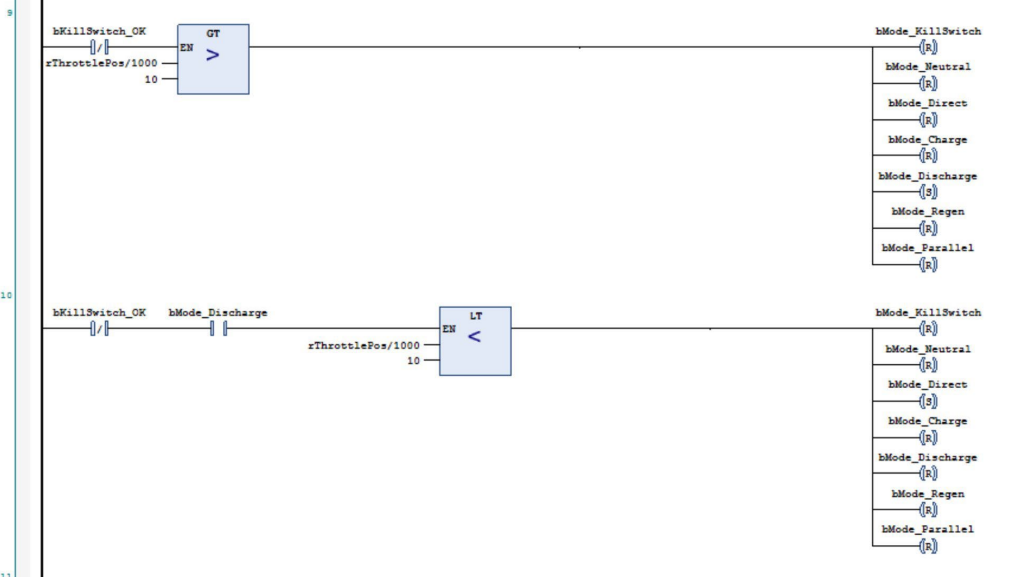
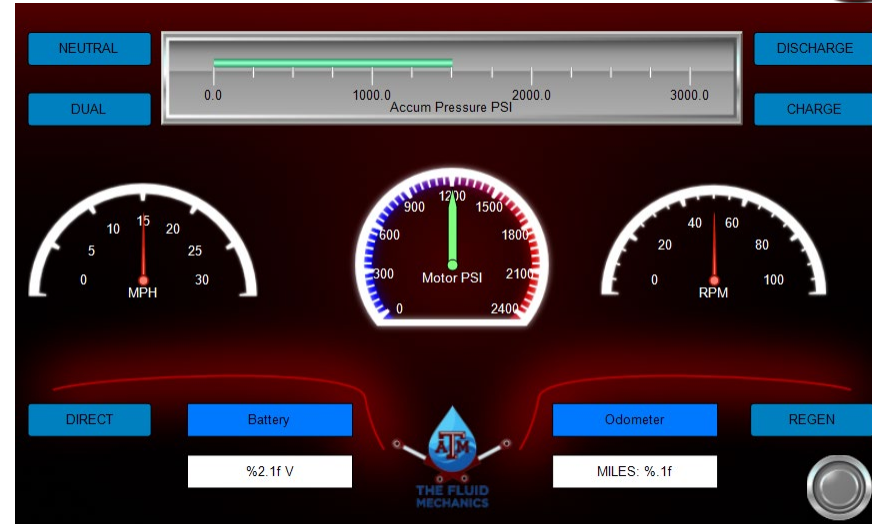
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ELECTRICAL



ELECTRICAL



```

(* ===== *)
(* PHYSICAL DIGITAL INPUTS (Buttons & Switches) *)
(* ===== *)
bBtn_DirectDrive : BOOL; (* Pin E15: Button for Direct Drive *)
bBtn_Neutral : BOOL; (* Pin E16: Button for Neutral *)
bBtn_Regen : BOOL; (* Pin E18: Digital signal from brake handle *)
bBtn_Parallel : BOOL; (* Pin E17: Button for Parallel Drive *)
bBtn_Charge : BOOL; (* Pin E10: Button for Accumulator Charge *)
bKillSwitch_OK : BOOL; (* Pin E04: Safety Loop (True=Safe, False=Kill) *)

(* ===== *)
(* PHYSICAL ANALOG INPUTS (Sensors) *)
(* ===== *)
rThrottlePos : REAL; (* Pin A06: 0.5V-4.5V Input from Throttle *)
rAccumulatorPres : REAL; (* Pin A18: Pressure Transducer 1 (PSI) *)
rMotorPres : REAL; (* Pin A05: Pressure Transducer 2 (PSI) *)
//rFlowRate : REAL; (* Pin A10: Transducer reading (GPM) *)

(* ===== *)
(* SYSTEM STATE INPUTS (Internal MCG Readings) *)
(* ===== *)
rBattery_Voltage : REAL; (* Resulting Voltage for local PLC logic *)

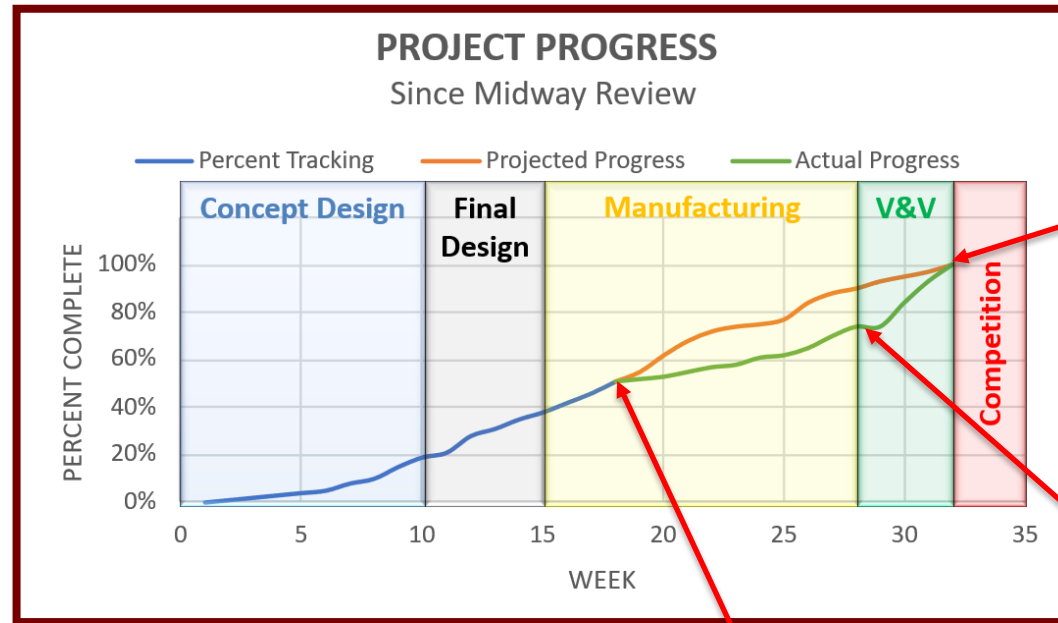
(* ===== *)
(* PHYSICAL DIGITAL OUTPUTS (Valves & Relays) *)
(* ===== *)
bValve_A : BOOL; (* Pin E02: DCV Solenoid 1 *)
bValve_B : BOOL; (* Pin E03: DCV Solenoid 2 *)
bValve_C : BOOL; (* Pin E08: DCV Solenoid 3 *)
bValve_D : BOOL; (* Pin E09: DCV Solenoid 4 *)
    
```

LESSONS LEARNED



- Technical Lessons:
 - Model mounts and fastener locations before manufacturing.
 - Use thinner mounting plates to save on weight.
 - Create second sprocket to allow for regen braking with CVT wheel.
 - Add Oil level dipstick to easily check oil amount.
 - Use thinner Aluminum plates for the frame instead to help with the vehicle weight
 - Conduct intermittent weight tests.
- Abstract Lessons:
 - Finishing a project without cutting corners takes a lot of dedication and time, even if it seems simple from the outside.
 - Your first design will probably not be the best option.
 - Small mistakes can turn into bigger problems, have contingencies for your contingencies.
 - Collaborating with others outside of the team can lead to a different perspective of your project and problem you're facing.
 - When sourcing components ensure vendors understand what you need and efficiently communicate with vendors to reduce miscommunication.
 - Do not procrastinate on the small things

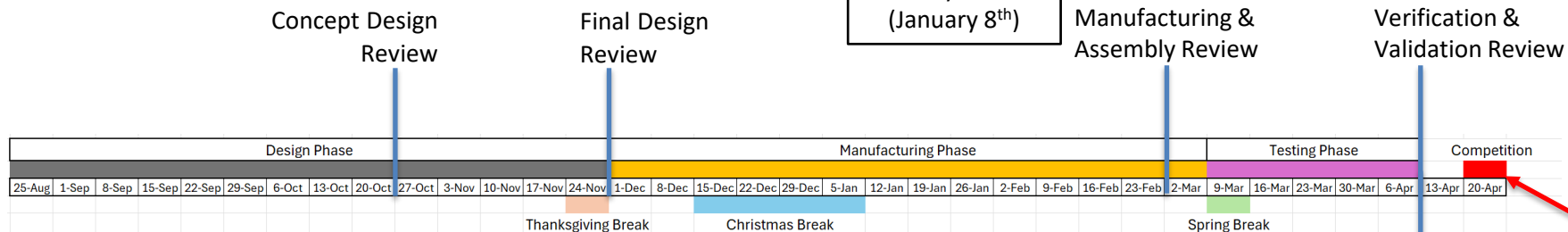
PROJECT TRACKING



Ship Date (April 10th)

Spring Break

Midway Review (January 8th)



We Are Here

Ship Date (April 10th)

FUTURE COMPETITORS



Justin Below
Class of '28

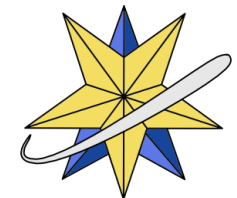
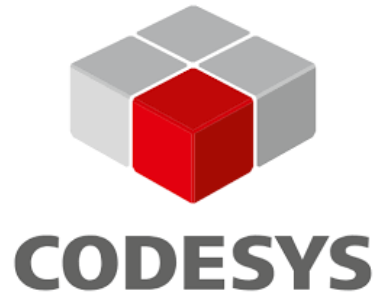
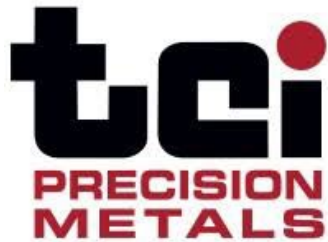


Jesus Munoz
Class of '28



Foster Cave
Class of '28

ACKNOWLEDGMENTS



Thank You, Questions?

